A General Framework For Computing the Nucleolus Via Dynamic Programming

Justin Toth

Joint work with Jochen Könemann



FACULTY OF MATHEMATICS Department of Combinatorics and Optimization • *n* players with value function $\nu : 2^{[n]} \to \mathbb{R}$



- n players with value function ν : 2^[n] → ℝ
- Comb Opt Games: ν optimizes a combinatorial structure



- n players with value function ν : 2^[n] → ℝ
- Comb Opt Games: ν optimizes a combinatorial structure
- Solution concepts assign payoffs to players







Cooperative Game Theory



 $\alpha \in [\mathsf{0},\mathsf{1}]$





• For allocation $x \in \mathbb{R}^n$, let

$$S_1,\ldots,S_{2^n-2}$$

be all proper coalitions in order of non-decreasing excess $ex(x, S) = x(S) - \nu(S)$:

• For allocation $x \in \mathbb{R}^n$, let

$$S_1,\ldots,S_{2^n-2}$$

be all proper coalitions in order of non-decreasing excess $ex(x, S) = x(S) - \nu(S)$:

$$\operatorname{ex}(x,S_1) \leq \operatorname{ex}(x,S_2) \leq \ldots \leq \operatorname{ex}(x,S_{2^n-2})$$

• For allocation $x \in \mathbb{R}^n$, let

$$S_1,\ldots,S_{2^n-2}$$

be all proper coalitions in order of non-decreasing excess $ex(x, S) = x(S) - \nu(S)$:

$$\operatorname{ex}(x, S_1) \leq \operatorname{ex}(x, S_2) \leq \ldots \leq \operatorname{ex}(x, S_{2^n-2})$$

• We define

$$\Theta(x) = (\operatorname{ex}(x, S_1), \dots, \operatorname{ex}(x, S_{2^n-2})).$$

• For allocation $x \in \mathbb{R}^n$, let

$$S_1,\ldots,S_{2^n-2}$$

be all proper coalitions in order of non-decreasing excess $ex(x, S) = x(S) - \nu(S)$:

$$\operatorname{ex}(x, S_1) \leq \operatorname{ex}(x, S_2) \leq \ldots \leq \operatorname{ex}(x, S_{2^n-2})$$

• We define

$$\Theta(x) = (\operatorname{ex}(x, S_1), \dots, \operatorname{ex}(x, S_{2^n-2})).$$

• Leastcore: allocations x, maximizing first coordinate of $\Theta(x)$

Definition: (Schmeidler 1969) The nucleolus of cooperative game (n, ν) is defined as

 $\eta(n,\nu) := \arg \operatorname{lex} \max_{x \in \mathbb{R}^n} \Theta(x)$



Definition: (Schmeidler 1969) The nucleolus of cooperative game (n, ν) is defined as

 $\eta(n,\nu) := \arg \operatorname{lex} \max_{x \in \mathbb{R}^n} \Theta(x)$

• The nucleolus is unique and in a sense "the most stable" allocation



Definition: (Schmeidler 1969) The nucleolus of cooperative game (n, ν) is defined as

 $\eta(n,\nu) := \arg \operatorname{lex} \max_{x \in \mathbb{R}^n} \Theta(x)$

- The nucleolus is unique and in a sense "the most stable" allocation
- (Aumann and Maschler 1985) Nucleolus explains certain wealth division applications in the Babylonian talmud.



• (Solymosi and Raghavan 1994) Efficient algorithm for finding nucleolus in (weighted) bipartite matching games

- (Solymosi and Raghavan 1994) Efficient algorithm for finding nucleolus in (weighted) bipartite matching games
- (Kuipers 1996) Efficient algorithm for finding nucleolus in convex games

- (Solymosi and Raghavan 1994) Efficient algorithm for finding nucleolus in (weighted) bipartite matching games
- (Kuipers 1996) Efficient algorithm for finding nucleolus in convex games
- Finding the nucleolus of MCST games is NP-hard (Faigle et al. 1998).

- (Solymosi and Raghavan 1994) Efficient algorithm for finding nucleolus in (weighted) bipartite matching games
- (Kuipers 1996) Efficient algorithm for finding nucleolus in convex games
- Finding the nucleolus of MCST games is NP-hard (Faigle et al. 1998).
- (Kern, Paulusma 2003) Can efficiently compute nucleolus in unweighted matching games

- (Solymosi and Raghavan 1994) Efficient algorithm for finding nucleolus in (weighted) bipartite matching games
- (Kuipers 1996) Efficient algorithm for finding nucleolus in convex games
- Finding the nucleolus of MCST games is NP-hard (Faigle et al. 1998).
- (Kern, Paulusma 2003) Can efficiently compute nucleolus in unweighted matching games
- Computing the nucleolus in network flow games is NP-hard (Deng, Fang, Sun 2009)

- (Solymosi and Raghavan 1994) Efficient algorithm for finding nucleolus in (weighted) bipartite matching games
- (Kuipers 1996) Efficient algorithm for finding nucleolus in convex games
- Finding the nucleolus of MCST games is NP-hard (Faigle et al. 1998).
- (Kern, Paulusma 2003) Can efficiently compute nucleolus in unweighted matching games
- Computing the nucleolus in network flow games is NP-hard (Deng, Fang, Sun 2009)
- Computing the nucleolus in weighted voting games is NP-hard (Elkind et al. 2007), and pseudo-polynomial time algorithms exist (Elkind and Pasechnik 2008), (Pashkovich 2018)

- (Solymosi and Raghavan 1994) Efficient algorithm for finding nucleolus in (weighted) bipartite matching games
- (Kuipers 1996) Efficient algorithm for finding nucleolus in convex games
- Finding the nucleolus of MCST games is NP-hard (Faigle et al. 1998).
- (Kern, Paulusma 2003) Can efficiently compute nucleolus in unweighted matching games
- Computing the nucleolus in network flow games is NP-hard (Deng, Fang, Sun 2009)
- Computing the nucleolus in weighted voting games is NP-hard (Elkind et al. 2007), and pseudo-polynomial time algorithms exist (Elkind and Pasechnik 2008), (Pashkovich 2018)
- (Baiou and Barahona 2019) Efficient algorithm for shortest path games.

- (Solymosi and Raghavan 1994) Efficient algorithm for finding nucleolus in (weighted) bipartite matching games
- (Kuipers 1996) Efficient algorithm for finding nucleolus in convex games
- Finding the nucleolus of MCST games is NP-hard (Faigle et al. 1998).
- (Kern, Paulusma 2003) Can efficiently compute nucleolus in unweighted matching games
- Computing the nucleolus in network flow games is NP-hard (Deng, Fang, Sun 2009)
- Computing the nucleolus in weighted voting games is NP-hard (Elkind et al. 2007), and pseudo-polynomial time algorithms exist (Elkind and Pasechnik 2008), (Pashkovich 2018)
- (Baiou and Barahona 2019) Efficient algorithm for shortest path games.
- (Könemann, Pashkovich, T. 2019) Can compute the nucleolus of weighted matching games in polynomial time.

Theorem 1: For a given cooperative game if the min excess problem: for any input $x \in \mathbb{R}^n$, find $S \subseteq [n]$ minimizing $x(S) - \nu(S)$, can be modelled with a dynamic program then the nucleolus of that game can be computed in time $O(n^6T)$ where T is the time it takes to solve the dynamic program.

Theorem 2: The min excess problem for *b*-matching games can be modelled with a dynamic program which can be solved in polynomial time if the underlying graph has bounded treewidth.

Corollary: On graphs of bounded treewidth the nucleolus of *b*-matching games can be computed in polynomial time.

Implicit in (Pashkovich 2018) is the following:

Lemma: If for any prime $p = O(n^2)$, $v \in \mathbb{F}_p^n$, and $q \in \mathbb{F}_p$ one can solve

$$\min\{x(S) - \nu(S) : v(S) \equiv p \mod p\}$$

in time T then one can compute the nucleolus in time O(poly(n)T).

Implicit in (Pashkovich 2018) is the following:

Lemma: If for any prime $p = O(n^2)$, $v \in \mathbb{F}_p^n$, and $q \in \mathbb{F}_p$ one can solve

$$\min\{x(S) - \nu(S) : v(S) \equiv p \mod p\}$$

in time T then one can compute the nucleolus in time O(poly(n)T).

Min excess problem:
 *ϵ*₁ = min{*x*(*S*) − *ν*(*S*) : *S* ⊆ [*n*]} ≡ separation oracle for leastcore points.

Implicit in (Pashkovich 2018) is the following:

Lemma: If for any prime $p = O(n^2)$, $v \in \mathbb{F}_p^n$, and $q \in \mathbb{F}_p$ one can solve

$$\min\{x(S) - \nu(S) : v(S) \equiv p \mod p\}$$

in time T then one can compute the nucleolus in time O(poly(n)T).

- Min excess problem:
 *ϵ*₁ = min{*x*(*S*) − *ν*(*S*) : *S* ⊆ [*n*]} ≡ separation oracle for leastcore points.
- To compute nucleolus need to separate 2nd min excess,..., and so on.

$$\min\{x(S) - \nu(S) : x(S) - \nu(S) \neq \epsilon_1, S \subseteq [n]\}$$

Implicit in (Pashkovich 2018) is the following:

Lemma: If for any prime $p = O(n^2)$, $v \in \mathbb{F}_p^n$, and $q \in \mathbb{F}_p$ one can solve

$$\min\{x(S) - \nu(S) : v(S) \equiv p \mod p\}$$

in time T then one can compute the nucleolus in time O(poly(n)T).

- Min excess problem:
 *ϵ*₁ = min{*x*(*S*) − *ν*(*S*) : *S* ⊆ [*n*]} ≡ separation oracle for leastcore points.
- To compute nucleolus need to separate 2nd min excess,..., and so on.

$$\min\{x(S) - \nu(S) : x(S) - \nu(S) \neq \epsilon_1, S \subseteq [n]\}$$

 Insight: x(S) − ν(S) ≠ ε₁ can be replaced with poly(n) congruency tests of the form

$$\min\{x(S) - \nu(S) : \nu(S) \equiv q \mod p, S \subseteq [n]\}$$

• *b*-matching games: each player *i* can form *b_i* partnerships.



• *b*-matching games: each player *i* can form *b_i* partnerships.



• *b*-matching games: each player *i* can form *b_i* partnerships.



- *b*-matching games: each player *i* can form *b_i* partnerships.
- min x(S) ν(S) where ν := max w-weight b-Matching on G[S].



- *b*-matching games: each player *i* can form *b_i* partnerships.
- min x(S) ν(S) where ν := max w-weight b-Matching on G[S].
- tree decomposition: Cover edges with bags of vertices.
- bag intersections form a tree structure.
- Size of largest bag 1 is treewidth



- C[ζ, F] := optimal solution on bags rooted at ζ using edges F in bag ζ.
- $C[\alpha, \{12\}] =$

$$\begin{split} \min x(12) - w(12) + C[\beta, F^{\beta}] + C[\delta, F^{\delta}] \\ \text{s.t.} F^{\beta} &\subseteq \{15\} \\ F^{\delta} &\subseteq \{23, 34, 24\} \\ |\{e \in F^{\beta} : 1 \in e\}| \leq 0 \\ |\{e \in F^{\delta} : 2 \in e\}| \leq 1 \end{split}$$



- C[ζ, F] := optimal solution on bags rooted at ζ using edges F in bag ζ.
- $C[\alpha, \{12\}] =$

$$\begin{split} \min x(12) &- w(12) + C[\beta, F^{\beta}] + C[\delta, F^{\beta}] \\ \text{s.t.} F^{\beta} &\subseteq \{15\} \\ F^{\delta} &\subseteq \{23, 34, 24\} \\ &|\{e \in F^{\beta} : 1 \in e\}| \leq 0 \\ &|\{e \in F^{\delta} : 2 \in e\}| \leq 1 \end{split}$$



Hypergraph Model of Dynamic Programming

• Dynamic program solutions: hyperpaths from root of Directed Acylic Hypergraph to leaves.



Hypergraph Model of Dynamic Programming

- Dynamic program solutions: hyperpaths from root of Directed Acylic Hypergraph to leaves.
- (Campbell, Martin, Rardin 1990) Convex Hull of Hyperpaths has compact extended formulation.



Hypergraph Model of Dynamic Programming

- Dynamic program solutions: hyperpaths from root of Directed Acylic Hypergraph to leaves.
- (Campbell, Martin, Rardin 1990) Convex Hull of Hyperpaths has compact extended formulation.
- How can we identify all hyperpaths *P* such that

$$\sum_{a\in P} v(a) \equiv q \mod p$$

for some
$$v \in \mathbb{F}_p^n$$
, $q \in \mathbb{F}_p$, prime p ?



Congruency Constrained Dynamic Programming

- Let $v \in \mathbb{F}_p^n$.
- Construct a new congruency hypergraph.



Congruency Constrained Dynamic Programming

- Let $v \in \mathbb{F}_p^n$.
- Construct a new congruency hypergraph.
- For each *q* ∈ 𝔽_{*p*} and for each node *u* in hypergraph do:
- Create node (u, q) to track hyperpaths P rooted at u of congruency v(P) ≡ q mod p.
- Heads of arc a_i should sum to $q v(a) \mod p$.



Conclusion

Results

- When we can solve the min excess problem efficiently with a dynamic program we can also compute the nucleolus efficiently
- The min excess problem of *b*-matching games can be modelled efficiently with a dynamic program on graphs of bounded treewidth
- The nucleolus of *b*-matching games can be computed efficiently on graphs of bounded treewidth

Conclusion

Results

- When we can solve the min excess problem efficiently with a dynamic program we can also compute the nucleolus efficiently
- The min excess problem of *b*-matching games can be modelled efficiently with a dynamic program on graphs of bounded treewidth
- The nucleolus of *b*-matching games can be computed efficiently on graphs of bounded treewidth

Open Problems

- Can we apply this framework to compute the nucleolus of other interesting games?
- Branched Polyhedral Systems (Kaibel and Loos 2010) are a common generalization of dynamic programming and disjunctive programming. Can our techniques extend to that setting?
- What is the complexity of computing the nucleolus of *b*-matching games in general?